

# Inertial Measurement Units Digital Tilt Sensors

## KERNEL

Datasheet Revision 2.6





The Inertial Labs MEMS KERNEL Inertial Measurement Units & Digital Tilt Sensors are the latest addition to the Inertial Labs Advanced Miniature MEMS sensor-based family. Revolutionary due to its very compact, self-contained strapdown, industrial-grade Inertial Measurement Systems that measures linear accelerations and angular rates with three-axis MEMS accelerometers and three-axis MEMS gyroscopes. Angular rates and accelerations are determined with low noise and very good repeatability for both motionless and dynamic applications.





KERNEL-100 (26 x 19 x 8 mm)

KERNEL-300 (26 x 19 x 12 mm)

The Inertial Labs KERNEL-100 & KERNEL-300 are the breakthrough, fully integrated inertial solution that combines the latest MEMS sensor technologies. Fully calibrated, temperature compensated, mathematically aligned to an orthogonal coordinate system, the IMU contains up to 1.5 deg/hr Bias in-run stability gyroscopes and 5 ug Bias in-run stability accelerometers with very low noise and high reliability.

Continuous Built-in Test (BIT), configurable communications protocols, electromagnetic interference (EMI) protection, and flexible input power requirements make the **Inertial Labs KERNEL** easy to use in a wide range of higher order integrated system applications.









The Inertial Labs KERNEL models were designed for applications, like:

- Autonomous vehicles
- Antenna and Line of Sight Stabilization Systems
- Passengers trains acceleration / deceleration and jerking systems
- Motion Reference Units (MRU) and Motion Control Sensors (MCS)
- Gimbals, EOC/IR, platforms orientation and stabilization
- GPS-Aided Inertial Navigation Systems (INS)
- Attitude and Heading Reference Systems (AHRS)
- Land vehicles navigation and motion analysis
- Buoy or Racing Boat Motion Monitoring
- UAV & AUV/ROV navigation and control

| Parameter                                   | KERNEL-100        | KERNEL-300      |  |  |  |
|---|-------------------|-----------------|--|--|--|
| GYROSCOPES                                  |                   |                 |  |  |  |
| Measurement range                           | ±2000 deg/sec     | ±2000 deg/sec   |  |  |  |
| Gyroscopes Bias in-run stability            | 2 deg/hr          | 1.5 deg/hr      |  |  |  |
| Gyroscopes Noise - Angular Random Walk      | 0.38 deg/vhr      | 0.08 deg/Vhr    |  |  |  |
| ACCELEROMETERS                              |                   |                 |  |  |  |
| Measurement range                           | up to ±40 g       | up to ±40 g     |  |  |  |
| Accelerometers Bias in-run stability        | 0.01 mg           | 0.005 mg        |  |  |  |
| Accelerometers Noise - Velocity Random Walk | 0.018 m/sec/Vhr   | 0.015 m/sec/Vhr |  |  |  |
| PITCH & ROLL ACCURACY                       | 0.05 deg 0.02 deg |                 |  |  |  |



### KERNEL-100 Preliminary Datasheet Revision 2.6

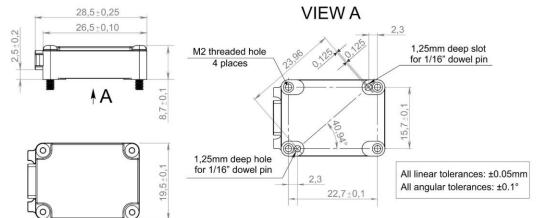
|                         | Personaler  | 11.75                    | KEDNEL 400   | 2 KEDNEL 200                   |  |
|-------------------------|---|--------------------------|--|--------------------------------|--|
|                         | Parameter   | Units                    |  | & KERNEL-300                   |  |
| GENERAL                 | Output signals  |                          | i  | ular Rates, Temperature, Synch |  |
|                         | Color of Enclosure  |                          | Black  |                                |  |
|                         | Update rate (IMU data)  | Hz                       | 2000 (4000 under development)                              |                                |  |
|                         | Update rate (Pitch & Roll data)                                       | Hz                       | 2000   |                                |  |
|                         | Start-up time   | sec                      | <0.02  |                                |  |
|                         | Full Accuracy Data (Warm-up Time)                                     | sec                      | <0.05  |                                |  |
|                         | Latency   | milli sec                | <1   |                                |  |
|                         | Pitch & Roll  | Units                    | KERNEL-100   | KERNEL-300                     |  |
|                         | Data rate   | Hz                       | 2000   | 2000                           |  |
|                         | Range: Pitch  | deg                      | ±90  | ±90                            |  |
|                         | Range: Roll   | deg<br>deg               | ±180<br>0.01   | ±180<br>0.01                   |  |
|                         | Angular Resolution  | deg, 1σ                  |  |                                |  |
|                         | Static Accuracy, RMS  |                          | 0.05   | 0.02                           |  |
|                         | Dynamic Accuracy, RMS   | deg, 1σ<br>Units         | 0.08   | 0.03                           |  |
|                         | Gyroscopes  | deg/sec                  | KERNEL-100   | KERNEL-300                     |  |
|                         | Measurement range   | Hz, 1σ                   | ±2000  | ±2000<br>260                   |  |
| 1                       | Bandwidth (-3dB) Data update rate                                     | Hz                       | 260  | 2000                           |  |
| 1                       |   | deg/hr, 1σ               | 2000   |                                |  |
| 111                     | Bias in-run stability (Allan Variance, RMS)                           |                          | 2 20   | 1.5<br>15                      |  |
| <u> </u>                | Bias repeatability (turn-on to turn-on, RMS)                          | deg/hr, 1σ<br>deg/hr, 1σ | 72   | 36                             |  |
| PERFORMANCE             | Bias instability (over temperature range, RMS)                        | ppm, 1σ                  |  |                                |  |
| Σ                       | SF accuracy (over temperature range) Noise. Angular Random Walk (ARW) | deg/√hr, 1σ              | 1000<br>0.38   | 1000<br>0.08                   |  |
| OR                      | Non-linearity   | ppm, 1σ                  | 350  | 200                            |  |
| ₹F(                     |   | mrad, 1σ                 | 0.15   | 0.15                           |  |
| Ä                       | Axis misalignment Accelerometers                                      | Units                    | KERNEL-100   | KERNEL-300                     |  |
|                         | Measurement range   | g                        | ±8 / ±15 / ±40   | ±8 / ±15 / ±40                 |  |
|                         | Bandwidth (-3dB)  | Ηz, 1σ                   | 260  | 260                            |  |
|                         | Data update rate  | Hz, 1σ                   | 2000   | 2000                           |  |
|                         | Bias in-run stability (RMS, Allan Variance)                           | mg, 1σ                   | 0.01 / 0.03 / 0.05   | 0.005 / 0.02 / 0.03            |  |
|                         | Bias instability (in temperature range, RMS)                          | mg, 1σ                   | 0.7 / 1.1 / 1.5  | 0.5 / 0.7 / 1.2                |  |
|                         | Bias one-year repeatability   | mg, 1σ                   | 1.5 / 2.0 / 2.5  | 1.0 / 1.3 / 1.5                |  |
|                         | SF accuracy (over temperature range)                                  | ppm, 1σ                  | 500 / 700 / 850  | 150 / 300 / 500                |  |
|                         | SF one-year repeatability   | ppm, 1σ                  | 800 / 1400 / 1700  | 500 / 1300 / 1500              |  |
|                         | Noise. Velocity Random Walk (VRW)                                     | m/sec/vhr, 1σ            | 0.02 / 0.045 / 0.06  | 0.015 / 0.035 / 0.015          |  |
|                         | Non-linearity   | ppm, 1σ                  | 340 / 800 / 1000   | 150 / 150 / 1000               |  |
|                         | Axis misalignment   | mrad, 1σ                 | 0.15 / 0.15 / 0.2  | 0.1 / 0.1 / 0.15               |  |
|                         | Environment   | Units                    |  | / KERNEL-300                   |  |
|                         |   |                          |  |                                |  |
|                         | Mechanical shock (MIL-STD-810G)                                       | g<br>gRMS, Hz            | 1500<br>8, 10 – 2000                                       |                                |  |
|                         | Vibration (MIL-STD-810G) Operating temperature                        | deg C                    | i  |                                |  |
| ٦                       | Storage temperature   | deg C                    | -40 to +85   |                                |  |
| 2                       |   | Pa, min                  | -50 to +90   |                                |  |
| Z                       | Low pressure  MTBF (G <sub>M</sub> @+65degC, operational)             | hours                    | 1750, 30   |                                |  |
| 王                       | , - 0, 1  | years                    | 100,000  |                                |  |
| ELECTRICAL & MECHANICAL | Life time (operational)  Life time (storage)                          |                          | 10   |                                |  |
| Σ                       | Electrical  | years<br>Units           | 17   |                                |  |
| જ                       | Supply voltage  | V DC                     | KERNEL-100 / KERNEL-300                                    |                                |  |
| AL                      |   | Watts                    | 4 to 15  |                                |  |
| 2                       | Power consumption   | vvdllS                   | 0.365 @ 5V<br>RS-422 (default), RS-232 (under development) |                                |  |
| H <sub>H</sub>          | Output Interface  | -                        |  |                                |  |
| EC.                     | Output data format  | -                        | Binary, ASCII (in GUI)  MIL-STD-461G                       |                                |  |
|                         | Physical EMC/EMI/ESD  | Units                    | KERNEL-100   | KERNEL-300                     |  |
| _                       | Physical  | mm                       |  |                                |  |
| 1                       | Size  |                          | 26.5 x 19.5 x 8.5  | 26.5 x 19.5 x 12               |  |
|                         | Weight  | grams                    | 7  | 20                             |  |

1σ specifications are manufactured to a controlled 3σ standard.

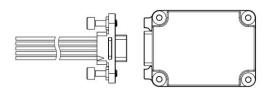


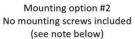
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#### **KERNEL-100 Mechanical Interface Descriptions**

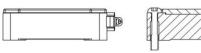


Mating screw-lock connector - G125-2241096F1



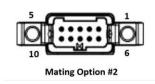


Mounting option #1 Captive screws from top side M2 x 10mm (SSBA-M2-10-A2)



Note: Suggested mounting screws are M2 x 10mm (92095A104) and can be included separately.

#### **KERNEL-100 Electrical Interface Descriptions**



| 1  | POWER   | Power Supply Input                   |
|----|---------|--------------------------------------|
| 2  | RESERV  | Reserved for future                  |
| 3  | RESERV  | Reserved for future                  |
| 4  | RS422-A | RS-422 Non-Inverting Input           |
| 5  | RS422-B | RS-422 Inverting Input               |
| 6  | GROUND  | Power Supply Return                  |
| 7  | TOV     | Time of validity output (by request) |
| 8  | EXTRIG  | External trigger input (by request)  |
| 9  | RS422-Y | RS-422 Non-Inverting Output          |
| 10 | RS422-Z | RS-422 Inverting Output              |

#### **KERNEL-100 Part Number Description**

| Model      | Gyroscope | Accel | Calibration | Connector | Color | Version | Interface   |
|------------|-----------|-------|-------------|-----------|-------|---------|-------------|
| KERNEL-100 | G2000     | A8    | TGA         | C12       | В     | V1      | 1           |
| KERNEL-300 |           | A15   |             | C22       |       |         | 2 (default) |
|            |           | A40   |             |           |       |         |             |

- G2000: Gyroscopes measurement range = ±2000 deg/sec
- A8: Accelerometers measurement range = ±8 g
- A15: Accelerometers measurement range = ±15 g
- A40: Accelerometers measurement range = ±40 g
- TGA: Gyroscopes and Accelerometers are calibrated over temperature range
- C12: Aluminum case, mounting option #1 mating option #2 (Captive screws; reference mechanical drawing)
   C22: Aluminum case, mounting option #2 mating option #2 (No screws included; reference mechanical drawing)
- B: Color Black
- V1: Version 1
- VX.1: RS-232 interface (under development)
- VX.2: RS-422 interface (default)

Example: KERNEL-100-G2000-A15-TGA-C12-B-V1.2