

RAILWAY MOTION CONTROL UNIT



EN 45545

EN 50155

EN 50011



RMCU

www.inertialabs.com

The **Railway Motion Control Unit - RMCU** is a high-performance strapdown system that was developed for Railway application in order to determine absolute orientation (Heading, Pitch and Roll) and parameters of motion (Angular Rates and Linear Accelerations) for any Railway Platforms on which it is mounted. Orientation is determined with high accuracy for both motionless and dynamic applications.



The Inertial Labs **RMCU** utilizes 3-axes each of precision MEMS accelerometers, miniature Fluxgate magnetometers and MEMS gyroscopes to provide accurate Heading, Pitch and Roll of the device under measure. Integration of gyroscopes' output provides high frequency, real-time measurement of the device rotation about all three rotational axes.

Accelerometers and Fluxgate magnetometer measure absolute, very accurate in static and dynamic conditions Pitch, Roll and Heading/Azimuth at RMCU initial alignment as well as providing ongoing corrections to gyroscopes during operation.

Parameter	RMCU
Heading static accuracy, RMS	0.3 deg
Heading dynamic accuracy in temperature range, RMS	0.6 deg
Pitch & Roll static accuracy, RMS	0.05 deg
Pitch & Roll dynamic accuracy in temperature range, RMS	0.08 deg
Dimensions	129 × 53 × 49 mm
Weight	120 grams
Interface	RS-485 / Ethernet

KEY FEATURES AND FUNCTIONALITY

- EN 45545, EN 50155 and EN 50011 Railway standards compliant solution
- One model with multiple configurations at an exceptional price performance ratio
- State-of-the-art algorithms for different Railway Platforms
- Highly accuracy miniature Fluxgate magnetometer
- Gyro-Stabilized Slaved Magnetic Heading
- Suitable for Trains Motion Control and Primary Attitude Reference
- Advanced Kalman Filter based sensor fusion algorithms
- Embedded 2D and 3D magnetic calibration on hard and soft iron
- All solid-state components (no moving parts)
- Full temperature calibration of all sensing elements
- Environmentally sealed (IP67)
- Compact design



One of the key elements to the success of Inertial Labs **RMCU** is its use of **mini Fluxgate Magnetometers**, which has distinct advantages over commonly used magneto-inductive or magneto-resistive magnetometers.

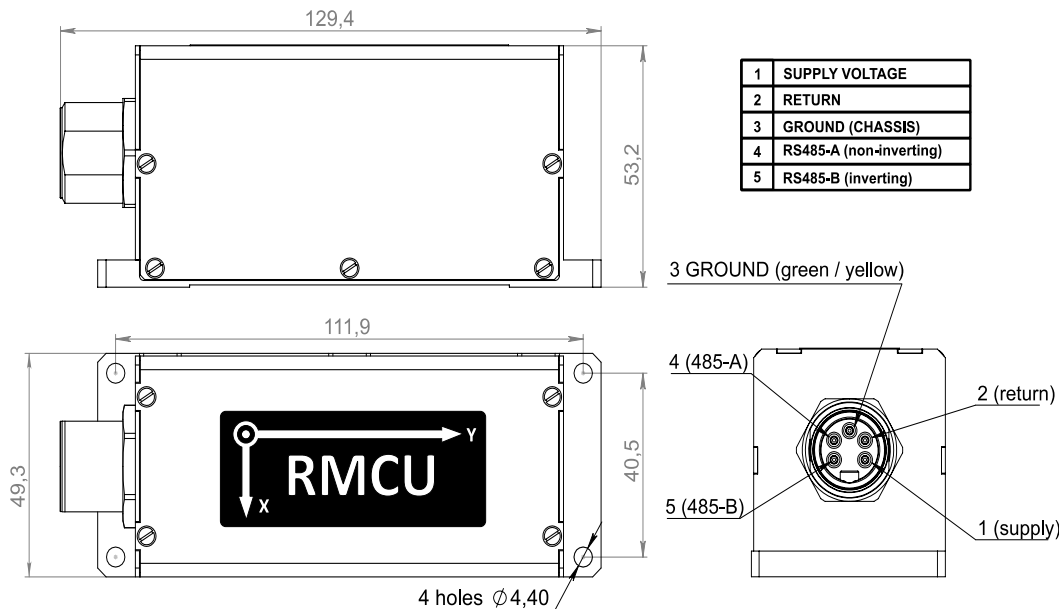
In operation over time and temperature fluxgate magnetometers have superior stability and repeatability. In terms of sensitivity, fluxgate magnetometers provide up to two orders of magnitude increased sensitivity.

In addition to the performance advantages, unlike the chip-level magnetometer technology, fluxgate magnetometer technology has been depended on for over 70 years to provide an accurate reference to North. It remains the most reliable magnetic sensor technology for determining an object's heading.

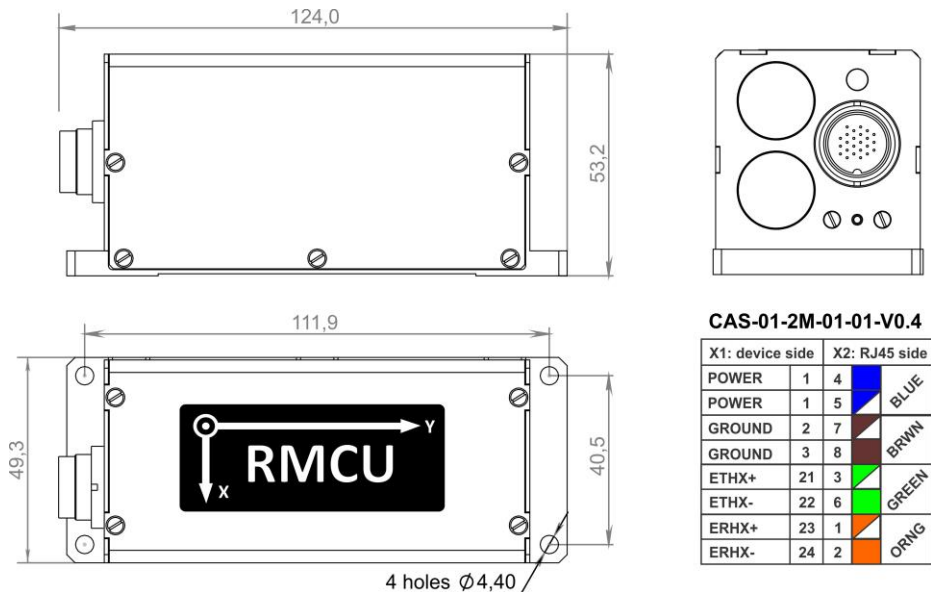
Parameter	Units	RMCU	
Output signals	Heading, Pitch, Roll; Quaternion; Accelerations; Angular rates; Magnetic field; Delta Theta & Delta Velocity		
Update rate	Hz	1 ... 2000 (user settable)	
Start-up time	sec	< 1	
Heading	Units	RMCU	
Range	deg	0 to 360	
Angular Resolution	deg	0.01	
Static Accuracy in Temperature Range	deg, 1σ	0.3	
Dynamic Accuracy	deg RMS, 1σ	0.6	
Pitch and Roll	Units	RMCU	
Range: Pitch, Roll	deg	±90, ±180	
Angular Resolution	deg	0.01	
Static Accuracy in Temperature Range	deg, 1σ	0.05	
Dynamic Accuracy	deg RMS, 1σ	0.08	
Gyroscopes	Units	RMCU	
Measurement range	deg/sec	±2000	
Bandwidth	Hz, 1σ	260	
Bias in-run stability (RMS, Allan Variance)	deg/hr, 1σ	2	
Bias residual error in temperature range, RMS	deg/hr, 1σ	72	
SF accuracy	ppm, 1σ	1000	
Noise. Angular Random Walk (ARW)	deg/√hr, 1σ	0.38	
Non-linearity	ppm, 1σ	100	
Axis misalignment	mrad, 1σ	0.15	
Accelerometers	Units	RMCU	
Measurement range	G	±8, ±15, ±40	
Bandwidth	Hz, 1σ	260	
Bias in-run stability (RMS, Allan Variance)	mg, 1σ	0.005, 0.02, 0.03	
Bias residual error in temperature range, RMS	mg, 1σ	0.5, 0.7, 1.2	
SF accuracy	ppm, 1σ	150, 300, 500	
Noise. Velocity Random Walk (VRW)	m/sec/√hr, 1σ	0.015, 0.035, 0.05	
Non-linearity	ppm, 1σ	150	
Axis misalignment	mrad, 1σ	0.15	
Magnetometers	Units	RMCU	
Measurement range	Gauss	±8.0	
Bias in-run stability, RMS	μGauss, 1σ	8	
Noise density, PSD	μGauss /√Hz, 1σ	15	
SF accuracy	ppm, 1σ	500	
Environment	Units	RMCU	
Operating temperature	deg C	-40 to +75	
Storage temperature	deg C	-50 to +85	
Operational Vibration	gRMS, Hz	7g, 20 – 2000 Hz	
Operational Shock	g, sec	40g, 0.01 sec	
MTBF (G _M)	hours	100,000	
Electrical & Physical	Units	RMCU	
Output Interface	-	RS-485	Ethernet
Connector		5 PINs	24 PINs
Supply voltage	V DC	3.3 to 7	9 to 36
Power consumption	Watts	0.5	0.9
Output data format		Binary, NMEA ASCII	Binary, NMEA ASCII
Size	mm	129.4 × 53.2 × 49.3	124 × 53.2 × 49.3
Weight	gram	120	120

1 σ specifications are manufactured to a controlled 3 σ standard.

RMCU interface drawing (RS-485 interface)



RMCU interface drawing (Ethernet interface)



Product Code Description

Model	Gyroscopes Range	Accelerometers Range	Calibration	Case and connector	Color	Version	Interface
RMCU-10	G2000	A8	TMGA	C34	B	V1.X	X.3
		A15		C3			X.5
		A40					
Example: RMCU-10-G2000-A8-TMGA-C34-B-V1.3 (RS-485)							
Example: RMCU-10-G2000-A8-TMGA-C3-B-V1.5 (Ethernet)							

- RMCU-10: Railway Motion Control Unit
- G2000: Gyroscopes measurement range = ± 2000 deg/sec
- A8: Accelerometers measurement range = ± 8 g
- A15: Accelerometers measurement range ± 15 g
- A40: Accelerometers measurement range ± 40 g
- TMGA: Magnetometers, Gyroscopes and Accelerometers
- C3: Aluminum case, IP67, 24 PIN connector (Ethernet interface)
- C34: Aluminum case, IP67, 5 PIN connector (RS-485 interface)
- V1X: Version 1
- X.3: RS-485 Interface (with C34 enclosure)
- X.5: Ethernet Interface (with C3 enclosure)